CMPUT 653: Theoretical Foundations of Reinforcement Learning, Winter 2022
Homework #3

Instructions

Submissions You need to submit a zip file, named `p3_<name>.zip` or `p3_<name>.pdf` where `<name>` is your name. The zip file should include a report in PDF, typed up (we strongly encourage to use pdfLATEX) and the code that we asked for. Write your name on your solution. I provide a template that you are encouraged to use. You have to submit the zip file on the eclass website of the course.

    Collaboration and sources Work on your own. You can consult the problems with your classmates, use books or web, papers, etc. Also, the write-up must be your own and you must acknowledge all the sources (names of people you worked with, books, webpages etc., including class notes.) Failure to do so will be considered cheating. Identical or similar write-ups will be considered cheating as well. Students are expected to understand and explain all the steps of their proofs.

    Scheduling Start early: It takes time to solve the problems, as well as to write down the solutions. Most problems should have a short solution (and you can refer to results we have learned about to shorten your solution). Don't repeat calculations that we did in the class unnecessarily.

    Deadline: March 14 at 11:55 pm

Tightness of performance bounds of greedy policies

Error bounds for greedy policies are at the heart of many of the upper bounds we obtained. Here you will be asked to show that these bounds are unimprovable. For example, in Lecture 6, the following is stated in Part II of the "Policy error bound - I." lemma:

Lemma 1. *Let π be a memoryless policy and choose a function $q : \mathcal{S} \times \mathcal{A} \to \mathbb{R}$ and $\epsilon \geq 0$. Then, if π is greedy with respect to q then*

$$v^\pi \geq v^* - \frac{2\|q - q^*\|_\infty}{1 - \gamma}\mathbf{1}\,.$$

    The first problem is to show that this bound is tight:

Question 1. Show that for any $\gamma \in [0, 1)$ and $\varepsilon > 0$ there is a finite discounted MDP $M = (\mathcal{S}, \mathcal{A}, P, r, \gamma)$ and $q : \mathcal{S} \times \mathcal{A} \to \mathbb{R}$ such that the following hold:

1. $\|q - q^*\|_\infty = \varepsilon$;

2. There is policy π that is greedy with respect to q such that $\|v^\pi - v^*\|_\infty = \frac{2\varepsilon}{1-\gamma}$.

Total: **10 points**

Average vs. mixed policies

Fix policies $\pi^{(1)}, \ldots, \pi^{(k)}$ of some finite discounted MDP $M = (\mathcal{S}, \mathcal{A}, P, r, \gamma)$. There are two ways of combining these policies with some weights $\alpha \in \mathcal{M}_1([k])$. The first way is to choose one of the policies at random from the multinomial parameterized by α and then follow the resulting policy for all the time steps. Formally, one would choose an index $I \in [k]$ at random such that $\mathbb{P}(I = i) = \alpha_i$ and then follow the policy $\pi^{(I)}$

for whichever state one encounters. The second way is to choose the policy to follow at random in each time step. Call the policy that is obtained following the first method the (α-weighted) **mixture of** $\pi^{(1)}, \ldots, \pi^{(k)}$. Call the policy that is obtained following the second method the (α-weighted) **average of** $\pi^{(1)}, \ldots, \pi^{(k)}$.

Intuitively, a distribution $\mu \in \mathcal{M}_1(\mathcal{S})$ over the states and the interconnection of a mixture policy and M gives rise to a probability space $(\Omega, \mathcal{F}, \mathbb{P})$ that carries the random elements $I, S_0, A_0, S_1, A_1, \ldots$ with $I \in [k]$, $S_t \in \mathcal{S}$ and $A_t \in \mathcal{A}$ for $t \geq 0$ and such that for $H_t = (S_0, A_0, S_1, \ldots, A_{t-1}, S_t)$,

1. $\mathbb{P}(S_0 = s|I) = \mu(s)$ for all $s \in \mathcal{S}$,

2. $\mathbb{P}(A_t = a|I, H_t) = \pi_t^{(I)}(a|H_t)$ for all $a \in \mathcal{A}, t \geq 0$,

3. $\mathbb{P}(S_{t+1} = s'|I, H_t, A_t) = P_{A_t}(S_t, s')$ for all $s' \in \mathcal{S}$, and

4. $\mathbb{P}(I = i) = \alpha_i$ for all $i \in [k]$.

Note that all first three criteria are modified to express that the laws that govern S_0, the action distribution and the next state distribution are as before even when conditioning on I. A new, fourth criterion is added that expresses that the distribution of I follows the multinomial distribution with parameter α. That the probability distribution $\mathbb{P}$ with the above properties exists is guaranteed again by the Ianescu-Tulcea theorem. As usual, when needed, we use $\mathbb{P}_\mu$ to indicate the dependence of $\mathbb{P}$ on μ.

Finally some notation: For a probability measure $\mathbb{P}$ on a measurable space $(\Omega, \mathcal{F})$ and a sub-sigma algebra $\mathcal{G}$ of $\mathcal{F}$, let $\mathbb{P}|_\mathcal{G}$ be the probability measure on $(\Omega, \mathcal{G})$ obtained from $\mathbb{P}$ by restricting it to $\mathcal{G}$: $\mathbb{P}|_\mathcal{G}(U) = \mathbb{P}(U)$ for any $U \in \mathcal{G}$.

Question 2. Unless otherwise specified let $\pi^{(1)}, \ldots, \pi^{(k)}$ be arbitrary policies of M and let $\alpha \in \mathcal{M}_1([k])$, $\mu \in \mathcal{M}_1(\mathcal{S})$ be also arbitrary. Also, let $(\Omega, \mathcal{F}, \mathbb{P})$ as above (we shall also use $\mathbb{P}_\mu$ when the dependence on μ is important). Let $Z = (S_0, A_0, S_1, A_1, \ldots)$. Show that the following hold:

1. Z is random element between $(\Omega, \mathcal{F})$ and $((\mathcal{S} \times \mathcal{A})^\mathbb{N}, \mathcal{G}')$ where $\mathcal{G}'$ is the product σ-algebra on $(\mathcal{S} \times \mathcal{A})^\mathbb{N}$ induced by the discrete topology on $\mathcal{S} \times \mathcal{A}$.

   5 points

2. Show that there is a policy $\bar{\pi}$ of the MDP M such that for any $\mu \in \mathcal{M}_1(\mathcal{S})$, the pushforward of $\mathbb{P}_\mu$ under Z, $(\mathbb{P}_\mu)_Z$ satisfies
   $$(\mathbb{P}_\mu)_Z = \mathbb{P}_\mu^{\bar{\pi}}$$
   where $\mathbb{P}_\mu^{\bar{\pi}}$ is the unique probability measure on the canonical space $((\mathcal{S} \times \mathcal{A})^\mathbb{N}, \mathcal{G}')$ induced by the interconnection of $\bar{\pi}$ and the MDP, given the initial state distribution μ. That is, a mixture policy induces a policy $\bar{\pi}$ of the MDP M.

   20 points

3. Let $R = \sum_{t=0}^\infty \gamma^t r_{A_t}(S_t)$ and let $\mathbb{P}$ be as above with the choice $\mu = \delta_s$. Let $\mathbb{E}$ be the expectation operator corresponding to $\mathbb{P}$. Show that $v(s) = \mathbb{E}[R]$ is well-defined: That is, for any $(\Omega, \mathcal{F}, \mathbb{P})$ and $(\Omega, \mathcal{F}, \mathbb{P}')$ as long as $\mathbb{P}$ and $\mathbb{P}'$ satisfy the above four properties, $\mathbb{E}[R] = \mathbb{E}'[R]$ where $\mathbb{E}'$ is the expectation operator underlying $\mathbb{P}'$.

   10 points

4. Show that $v(s) = v^{\bar{\pi}}(s)$.

   5 points

5. Let $\mathbb{P}_\mu^{\pi^{(i)}}$ ($\mathbb{P}_\mu^{\bar{\pi}}$) be the probability measures induced on the canonical space $((\mathcal{S} \times \mathcal{A})^{\mathbb{N}}, \mathcal{G}')$ by the initial state distribution μ and the interconnection of $\pi^{(i)}$ (respectively, $\bar{\pi}$) with the MDP M. Show that $\mathbb{P}_\mu^{\bar{\pi}} = \sum_{i=1}^{k} \alpha_i \mathbb{P}_\mu^{\pi^{(i)}}$.

10 points

6. Mixing is guaranteed to keep performance bounds: if for some $v : \mathcal{S} \to \mathbb{R}$ and for all $i \in [k]$, $v^{\pi^{(i)}} \geq v$ then $v^{\bar{\pi}} \geq v$.

5 points

7. Averaging is not guaranteed to keep performance bounds: For any $\gamma > 1/2$ there exists an MDP with state space $\mathcal{S}$, $k \geq 2$, policies $\pi_1, \ldots, \pi_k$, a function $v : \mathcal{S} \to \mathbb{R}$ and $\alpha \in \mathcal{M}_1([k])$ such that $v^{\pi_i} \geq v$ holds for all $i \in [k]$, yet if π is the α-average of $\pi_1, \ldots, \pi_k$ then $v^\pi < v$.

10 points

8. The state-wise uniform average of all deterministic ML policies and the uniform mixture of all deterministic ML policies both give the policy that is uniform over all the actions.

5 points

Hint: Recall the change-of-variables formula: For a random element X taking values in some measurable set $\mathcal{X}$, the pushforward $\mathbb{P}_X$ of X satisfies

$$\mathbb{E}[f(X)] = \int f(x) \mathbb{P}_X(dx) \, .$$

Recall also that integration is linear in measures. In particular, for any measures $\mathbb{P}_i$ and nonnegative coefficients α_i, $i \in [k]$ and f which is $(\sum_{i=1}^{k} \alpha \mathbb{P}_i)$-integrable, $\int f d(\sum_{i=1}^{k} \alpha \mathbb{P}_i) = \sum_{i=1}^{k} \alpha_i \int f d\mathbb{P}_i$ (this also extends to signed measures, but we won't need this extension).

Total: **70 points**

Finding needles with high probability

The high-probability needle lemma is as follows:

Lemma 2 (High-probability needle lemma). *Any algorithm that correctly identifies the single nonzero entry in any binary array of length k with probability at least 0.91 has the property that on some input the expected number of queries that the algorithm uses is at least $\Omega(k)$.*

Question 3. Prove Lemma 2. Note that the algorithms are allowed to randomize.

Total: **30 points**

Total for all questions: 110. Of this, up to 20 can be bonus marks. You can receive bonus marks by asking/upvoting questions, for a total of 20 bonus marks! You must ask at least one question in one of the Lecture Discussion Threads by the Assignment 3 deadline to receive 12 bonus marks. You can also receive 2 bonus marks for upvoting at least one question before 8am on the day of each lecture, for a maximum of 2 marks x 4 lectures = 8 marks for upvoting. Your assignment will be marked out of 110 minus the bonus marks you received.